

Continuous RVs Continued: Independence, Conditioning, Gaussians, CLT

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Lecture 25, 8/6/19



Independence, Continued

If X, Y are independent, their joint density is the product of their individual densities:

$$f_{X,Y}(x,y) =$$

Example: If X, Y are independent exponential RVs with parameter λ :



Not Too Different From Discrete...

Discrete RV:

X and Y are independent iff for all a, b :

$$\mathbb{P}[X = a, Y = b] = \mathbb{P}[X = a] \cdot \mathbb{P}[Y = b]$$

Continuous RV:

X and Y are independent iff for all $a \leq b, c \leq d$:

$$\mathbb{P}[a \leq X \leq b, c \leq Y \leq d] =$$



Example: Max of Two Exponentials

Let $X \sim \text{Expo}(\lambda)$ and $Y \sim \text{Expo}(\mu)$.

X and Y are **independent**.

Compute $\mathbb{P}[\max(X, Y) \geq t]$.

Use this to compute $\mathbb{E}[\max(X, Y)]$.



A Note on Independence

For continuous RVs, what is weird about the following?

$$\mathbb{P}[X = a, Y = b] = \mathbb{P}[X = a] \cdot \mathbb{P}[Y = b]$$

What we **can** do: consider a interval of length dx around a and b !



Min of n Uniforms

Let X_1, \dots, X_n be **i.i.d.** and uniform over $[0, 1]$.

What is $\mathbb{P}[\min(X_1, \dots, X_n) \leq x]$?

Use this to compute $\mathbb{E}[\min(X_1, \dots, X_n)]$.



Min of n Uniforms

What is the CDF of $\min(X_1, \dots, X_n)$?

What is the PDF of $\min(X_1, \dots, X_n)$?

Memorylessness of Exponential

We can't talk about independence without talking about **conditional probability!**

Let $X \sim \text{Expo}(\lambda)$. X is **memoryless**, i.e.

$$\mathbb{P}[X \geq s + t | X > t] = \mathbb{P}[X \geq s]$$

Conditional Density

What happens if we condition on events like $X = a$? These have 0 probability!

The same story as discrete, except we now need to define a conditional **density**:

$$f_{Y|X}(y|x) = \frac{f_{X,Y}(x,y)}{f_X(x)}$$

Think of $f(y|x)$ as

$$\mathbb{P}[Y \in [y, y + dy] | X \in [x, x + dx]]$$

Conditional Density, Continued

Given a conditional density $f_{Y|X}$, compute

$$\mathbb{P}[Y \leq y | X = x] =$$

If we know $\mathbb{P}[Y \leq y | X = x]$, compute

$$\mathbb{P}[Y \leq y] =$$

Go with your gut! What worked for discrete also works for continuous.

Example: Sum of Two Exponentials

Let X_1, X_2 be **i.i.d** $\text{Expo}(\lambda)$ RVs.

Let $Y = X_1 + X_2$.

What is $\mathbb{P}[Y < y | X_1 = x]$?

What is $\mathbb{P}[Y < y]$?

Example: Total Probability Rule

What is the CDF of Y ?

What is the PDF of Y ?

Break

If you could immediately gain one new skill, what would it be?

The Normal (Gaussian) Distribution

X is a **normal** or **Gaussian** RV if:

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \cdot e^{-(x-\mu)^2/2\sigma^2}$$

Parameters:

Notation: $X \sim$

$\mathbb{E}[X] =$ $\text{Var}(X) =$

Standard Normal:

Gaussian Tail Bound

Let $X \sim \mathcal{N}(0, 1)$.

Easy upper bound on $\mathbb{P}[|X| \geq \alpha]$, for $\alpha \geq 1$?
(Something we've seen before...)

Gaussian Tail Bound, Continued

Turns out we can do better than Chebyshev.

Idea: Use $\int_{\alpha}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx \leq$

Shifting and Scaling Gaussians

Let $X \sim \mathcal{N}(\mu, \sigma)$ and $Y = \frac{X-\mu}{\sigma}$. Then:

$Y \sim$

Proof: Compute $\mathbb{P}[a \leq Y \leq b]$.

Change of variables: $x = \sigma y + \mu$.

Shifting and Scaling Gaussians

Can also go the other direction:

If $X \sim \mathcal{N}(0, 1)$, and $Y = \mu + \sigma X$:
 Y is still Gaussian!

$\mathbb{E}[Y] =$

$\text{Var}(Y) =$

Sum of Independent Gaussians

Let X, Y be **independent** standard Gaussians.

Let $Z = [aX + c] + [bY + d]$.

Then, Z is **also Gaussian!** (Proof optional.)

$$\mathbb{E}[Z] =$$

$$\text{Var}(Z) =$$

Example: Height

Consider a family of a two parents and twins with the same height. The parents' heights are independently drawn from a $\mathcal{N}(65, 5)$ distribution. The twins' height are independent of the parents', and from a $\mathcal{N}(40, 10)$ distribution.

Let H be the sum of the heights in the family. Define relevant RVs:

Example: Height

$$\mathbb{E}[H] =$$

$$\text{Var}[H] =$$

Sample Mean

We sample a RV X **independently** n times. X has mean μ , variance σ^2 .

Denote the **sample mean** by $A_n = \frac{X_1 + X_2 + \dots + X_n}{n}$

$$\mathbb{E}[X] =$$

$$\text{Var}(X) =$$

The Central Limit Theorem (CLT)

Let X_1, X_2, \dots, X_n be **i.i.d.** RVs with mean μ , variance σ^2 . (Assume mean, variance, are finite.)

Sample mean, as before: $A_n = \frac{X_1 + X_2 + \dots + X_n}{n}$

Recall: $\mathbb{E}[A_n] =$

$\text{Var}(A_n) =$

Normalize the sample mean:

$$A'_n =$$

Then, as $n \rightarrow \infty$, $\mathbb{P}[A'_n] \rightarrow$

Example: Chebyshev vs. CLT

Let X_1, X_2, \dots be **i.i.d** RVs with $\mathbb{E}[X_i] = 1$ and $\text{Var}(X_i) = \frac{1}{2}$. Let $A_n = \frac{X_1 + X_2 + \dots + X_n}{n}$.

$$\mathbb{E}[A_n] =$$

$$\text{Var}(A_n) =$$

Normalize to get A'_n :

Example: Chebyshev vs. CLT

Upper bound $\mathbb{P}[A'_n \geq 2]$ for **any** n .
(We don't know if A'_n is **non-neg** or **symmetric**.)

If we take $n \rightarrow \infty$, upper bound on $\mathbb{P}[A'_n \geq 2]$?

Summary

- ▶ Independence and conditioning also generalize from the **discrete** RV case.
- ▶ The Gaussian is a very important continuous RV. It has several nice properties, including the fact that adding independent Gaussians gets you another Gaussian
- ▶ The CLT tells us that if we take a **sample average** of a RV, the distribution of this average will approach a **standard normal**.